

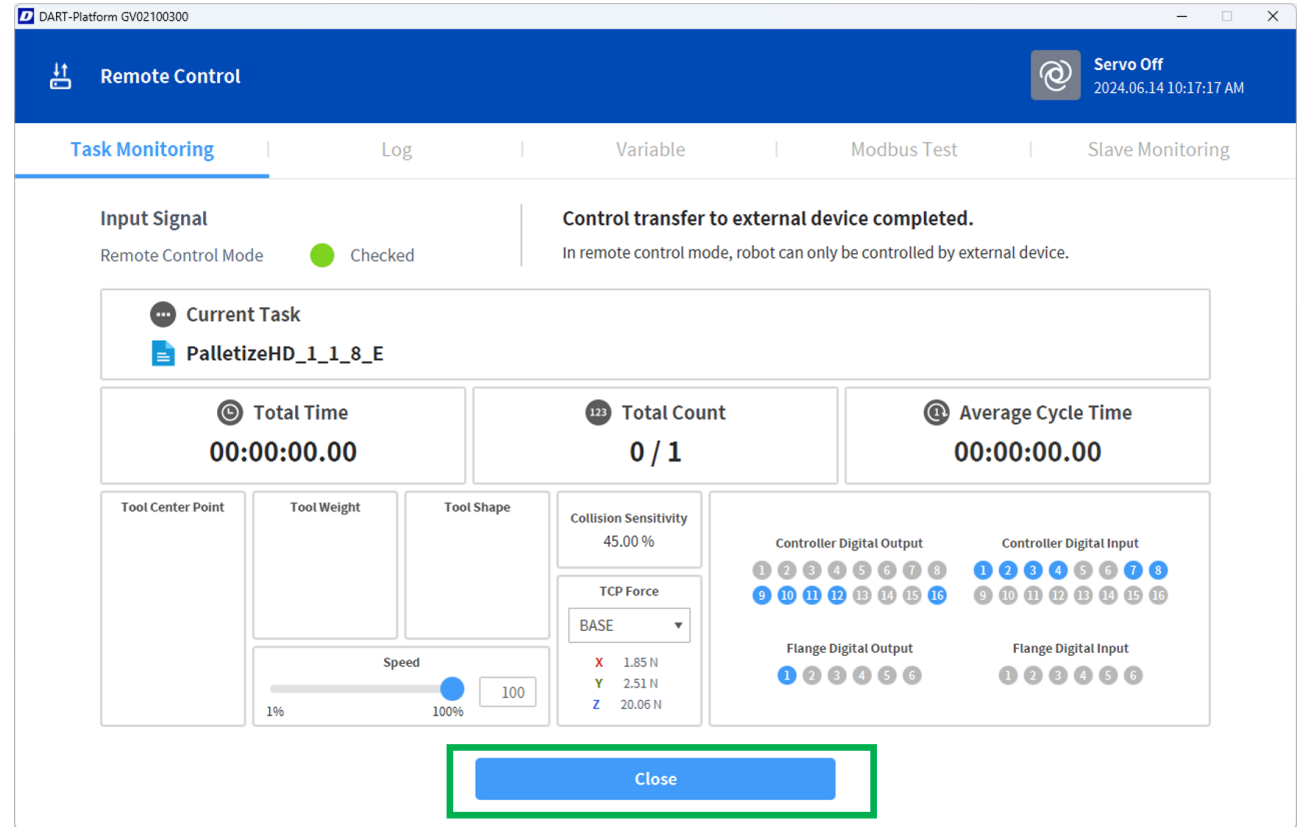
Step 1

Open access door on robot
and remove pendant



Step 2

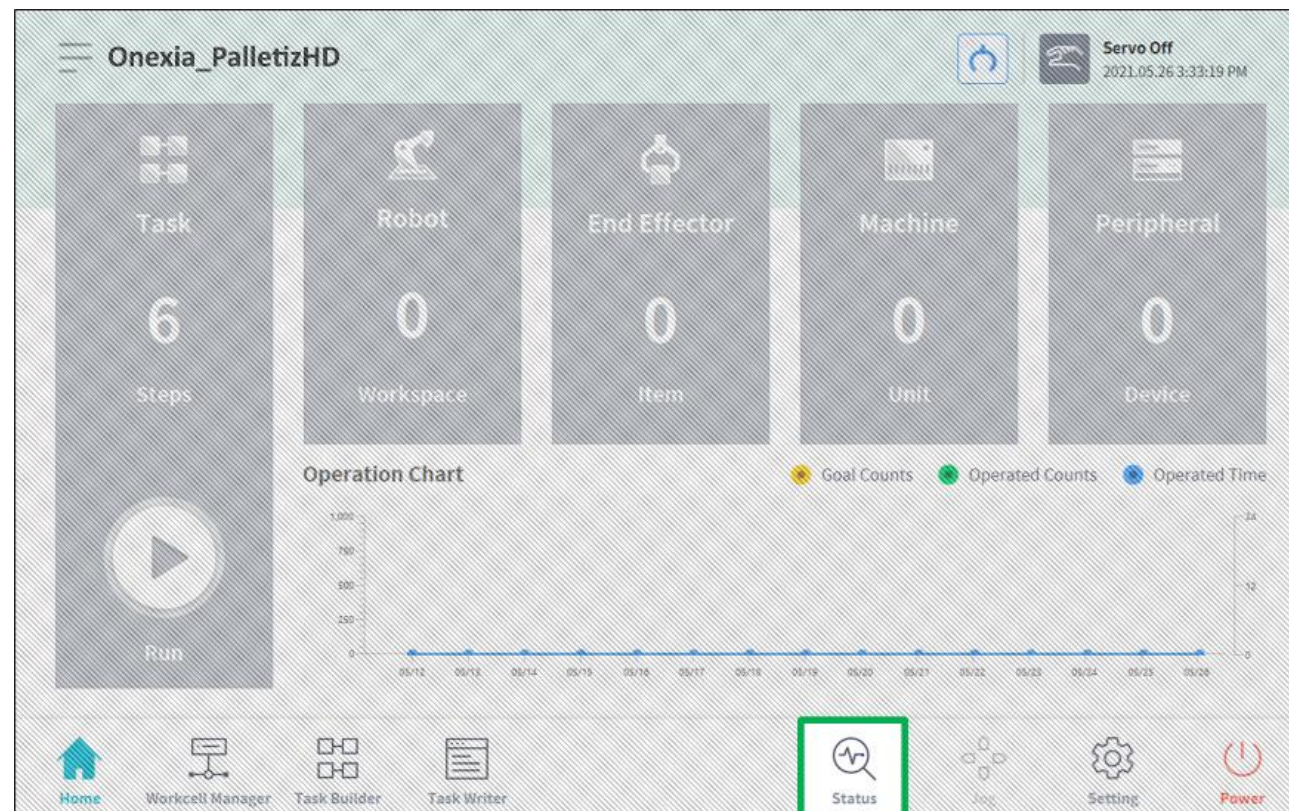
Use the 'Close' button at the bottom of the screen to exit remote control mode



Step 3

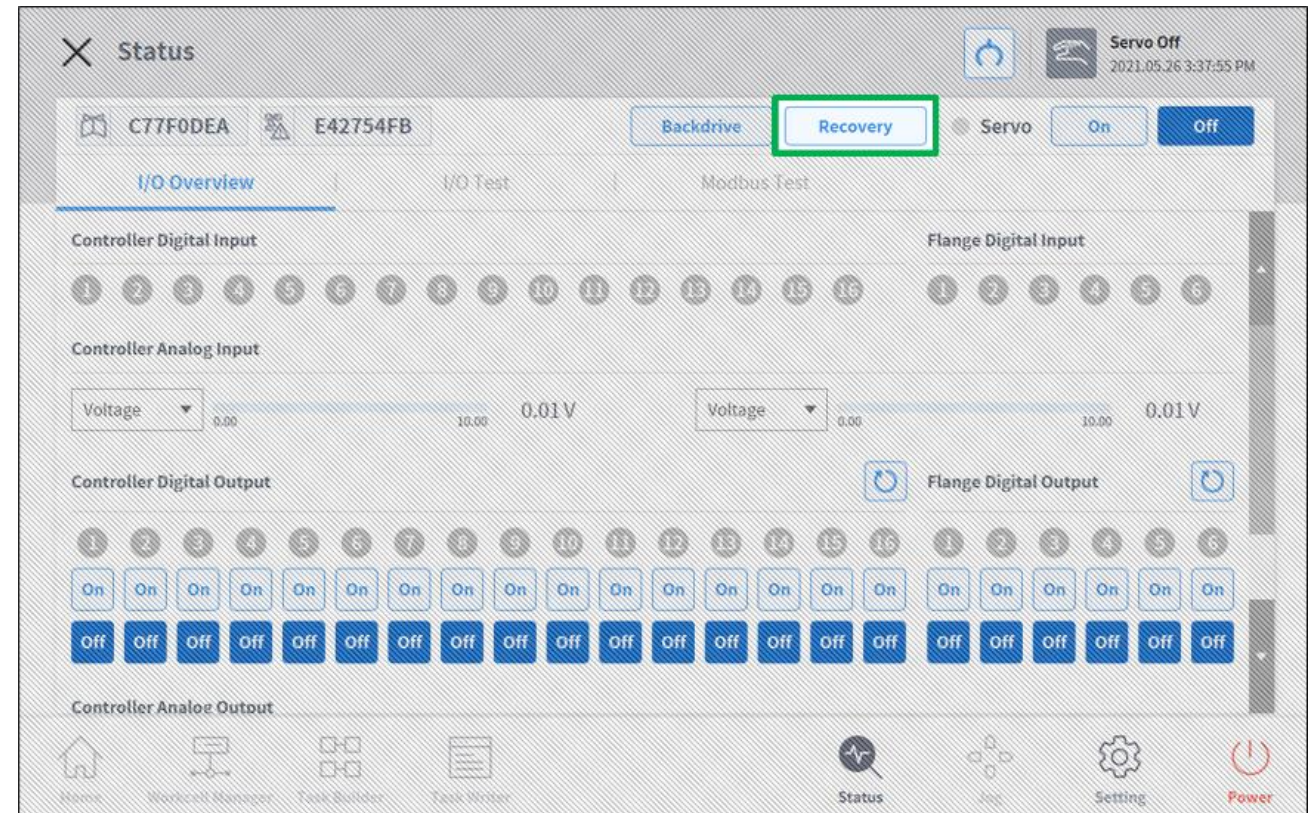
Click the 'Status' button at
The bottom of the screen

If the status button is grayed
out, click the 'X' or '<' button
in the upper-left corner of
the screen.



Step 4

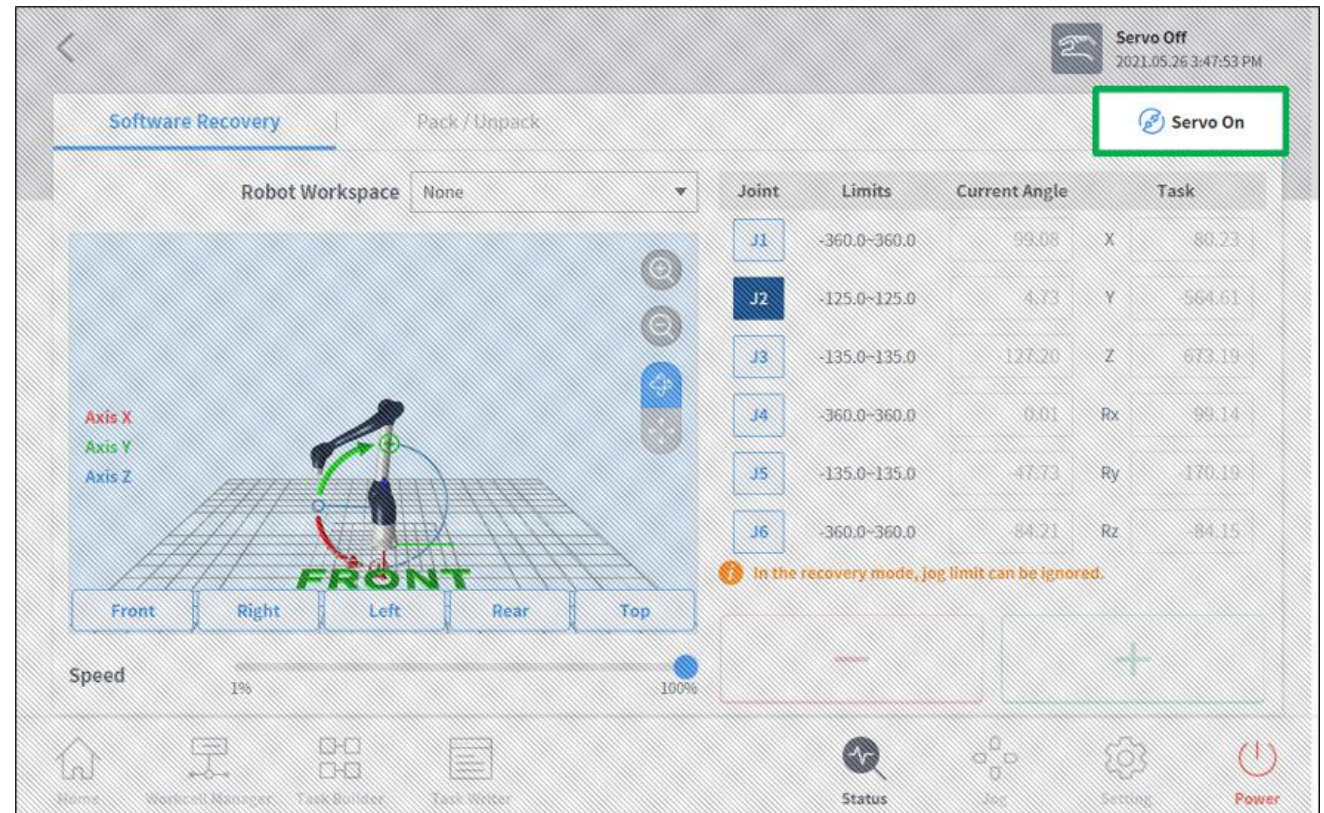
Click the 'Recovery' button on the status screen.



Step 5

Click the 'Servo On' to turn the robot motors on.

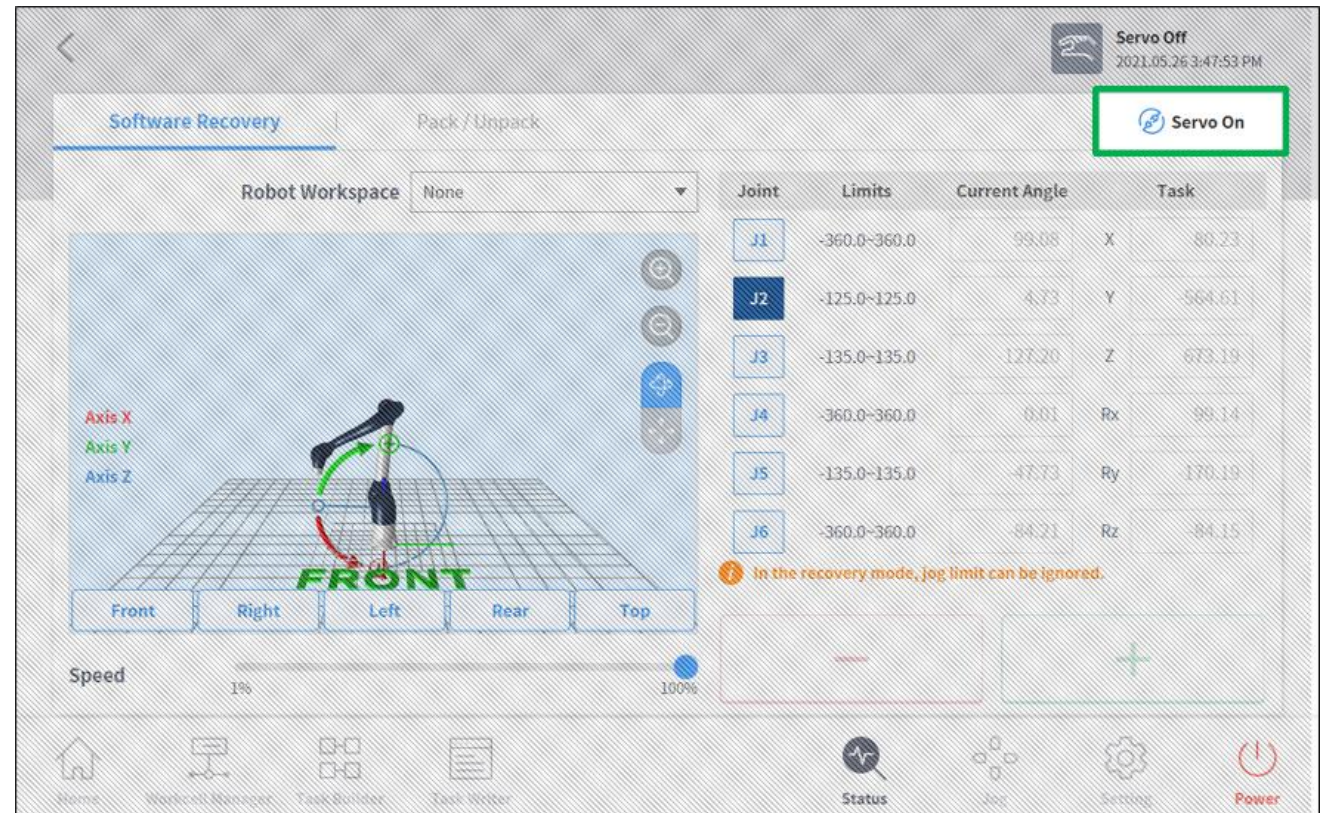
Robot lights should change from red to yellow.



Step 6

Click the 'Servo On' to turn the robot motors on.

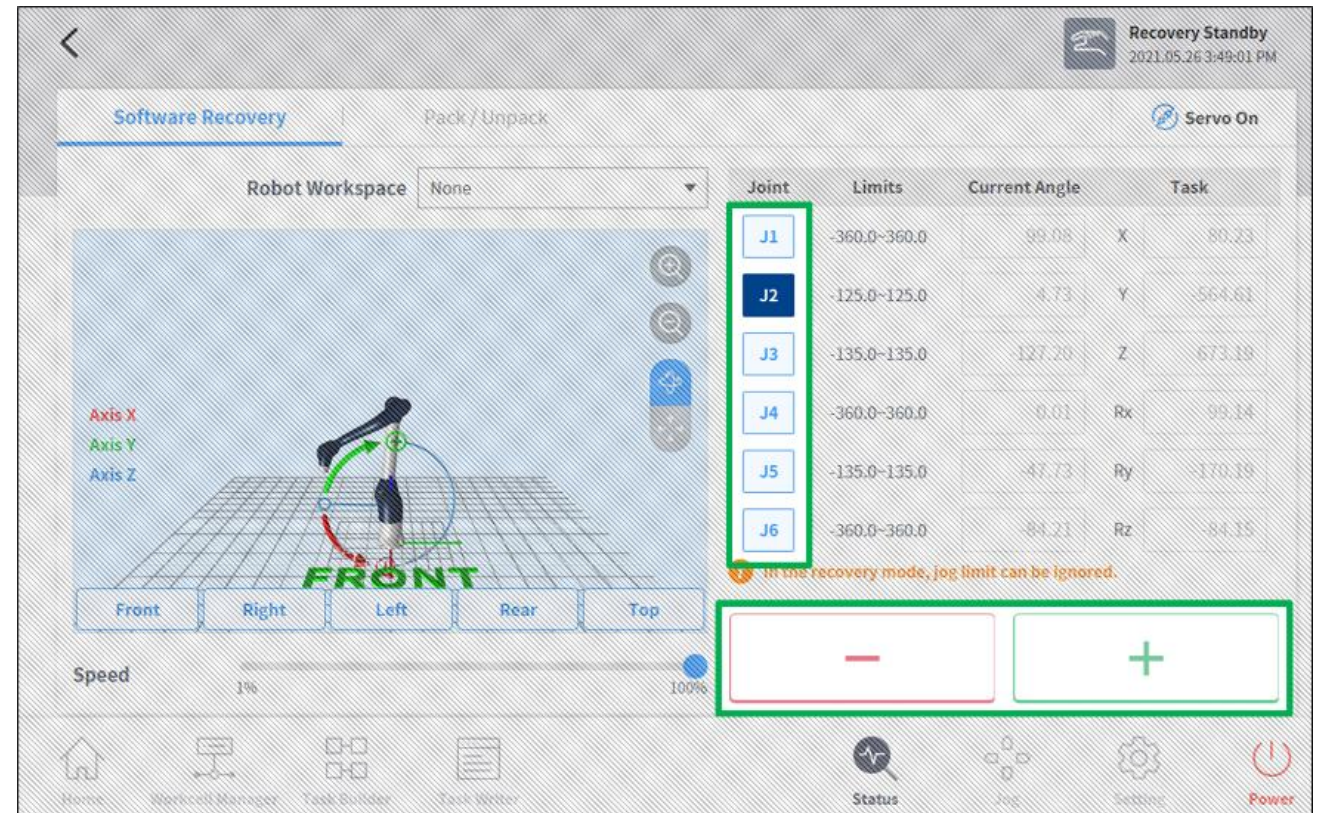
Robot lights should change from red to yellow.



Step 7

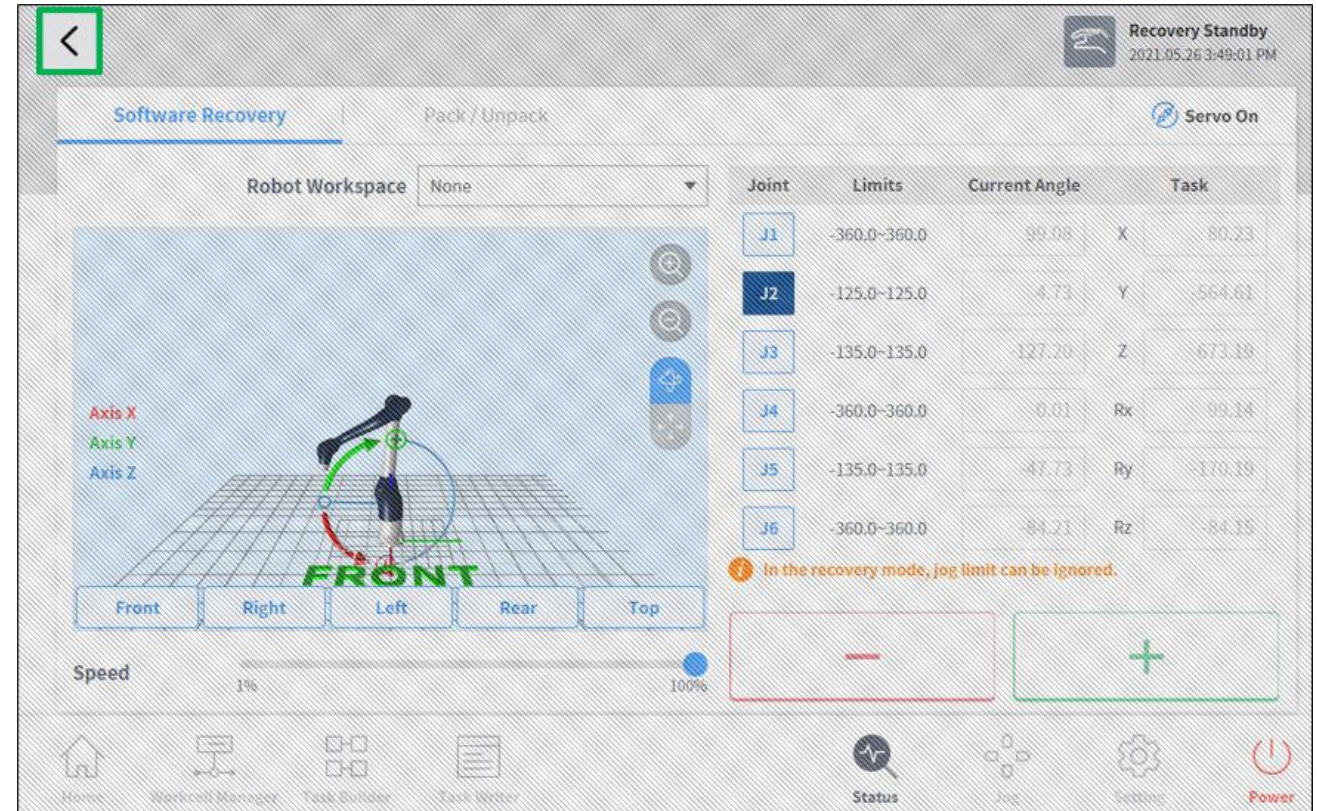
Use the select the joint to move and jog it back into the needed range.

If J6 was past 360 degrees, move it to 0 degrees.



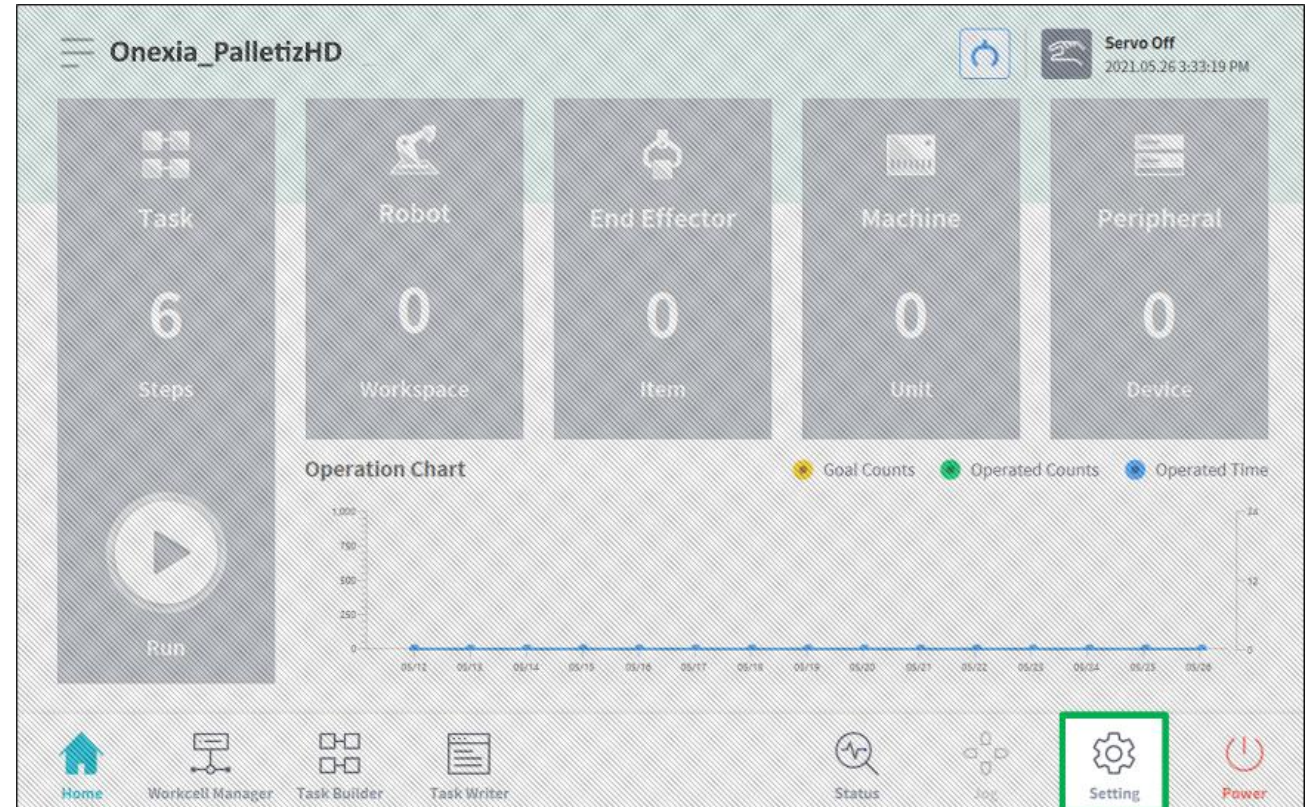
Step 8

Use the '<' button in the upper-left of the screen to exit recovery mode.



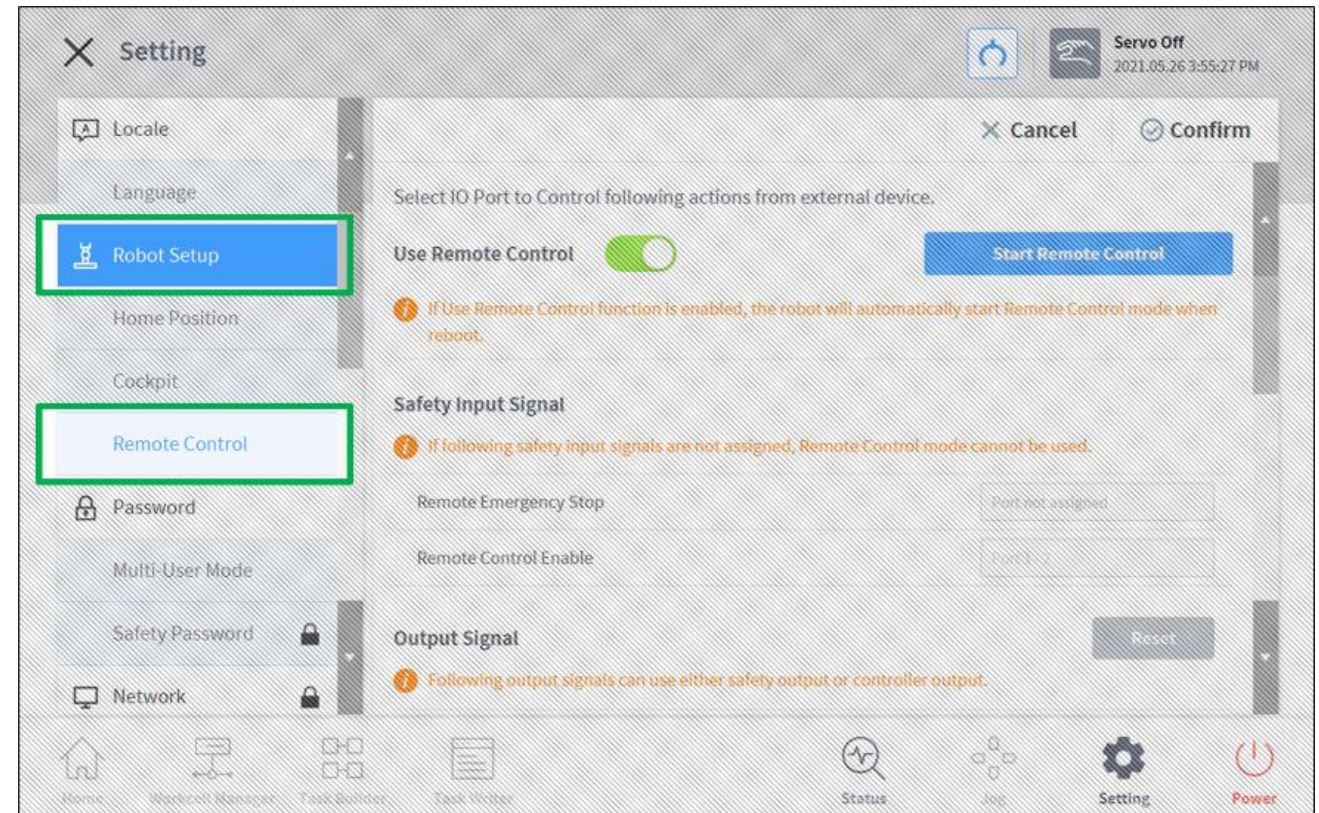
Step 9

Press the 'Setting' button.



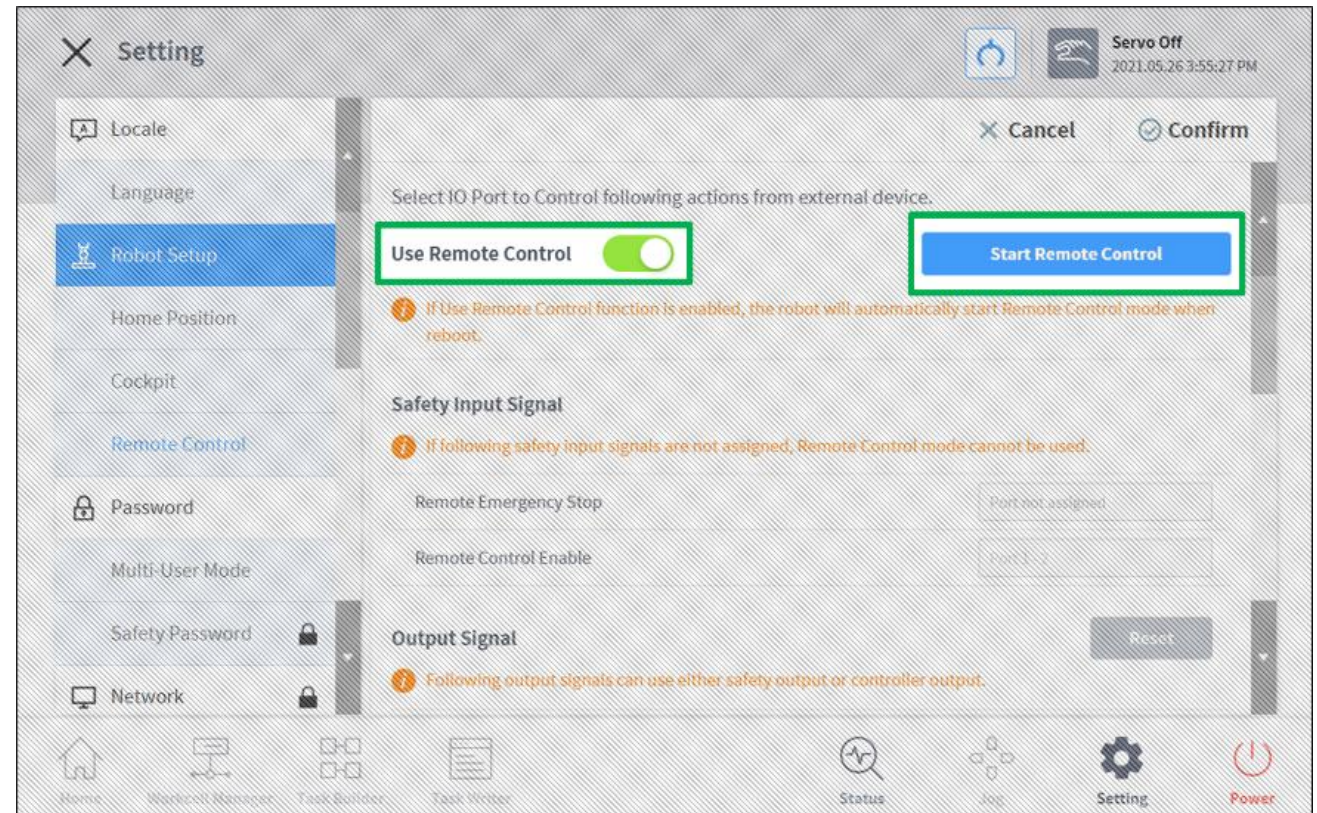
Step 10

In the settings, go to 'Robot Setup' and select 'Remote Control'.



Step 11

Make sure 'Use Remote Control' is on and press 'Start Remote Control'.



Step 12

System should be in ‘Remote Control’ mode.

Replace access pendant and resume normal operation with the enable robot and start robot buttons on the main screen.

